

OpenAir ${ }^{\text {TM }}$

## Air damper actuators

Electronic motor driven actuators for three-position and modulating control, nominal torque 15 Nm , self-centering shaft adapter, mechanically adjustable span between $0 . . .90^{\circ}$, prewired with 0.9 m long connection cables. Type-specific variations with adjustable offset and span for the positioning signal, position indicator, feedback potentiometer, self-adaptation of the rotary angle range, and adjustable auxiliary switches for supplementary functions.

Remarks
This data sheet provides a brief overview of these actuators. Please refer to the technical basics in CM2Z4621en for a detailed description as well as information on safety, engineering notes, mounting and commissioning.

Use

- For damper areas up to $3 \mathrm{~m}^{2}$, friction-dependent.
- Suitable for modulating controllers (DC $0 \ldots .10 \mathrm{~V}$ ) or three-position controllers (e.g. for outside air dampers).
- For dampers having two actuators on the same damper shaft (tandem-mounted actuators or Powerpack).

Type summary

| GEB.... | 131.1E | 132.1E | 136.1E | 331.1E | 332.1E | 336.1E | 161.1E | 163.1E | 164.1E | 166.1E |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Control type | Three-position control |  |  |  |  |  | Modulating control |  |  |  |
| Operating voltage AC 24 V | X | X | X |  |  |  | X | X | X | X |
| Operating voltage <br> AC 230 V |  |  |  | X | X | X |  |  |  |  |
| Positioning signal Y $\text { DC } 0 \ldots . .10 \mathrm{~V}$ |  |  |  |  |  |  | X | X | X | X |
| DC $2 \ldots .10 \mathrm{~V}$ |  |  |  |  |  |  | X |  |  | X |
| DC $0 . . .35 \mathrm{~V}$ with characteristic function Uo, $\Delta \mathrm{U}$ |  |  |  |  |  |  |  | X | X |  |
| Position indicator $\mathrm{U}=\mathrm{DC} 0 \ldots 10 \mathrm{~V}$ |  |  |  |  |  |  | X | X | X | X |
| Feedback potentiometer $1 \mathrm{k} \Omega$ |  | X |  |  | X |  |  |  |  |  |
| Self-adaptation of rotary angle range |  |  |  |  |  |  | X | X | X | X |
| Auxiliary switches (two) |  |  | x |  |  | x |  |  | X | X |
| Rotary direction switch |  |  |  |  |  |  | X | X | X | X |
| Powerpack (two actuators, tandem-mounted) | X | X | X | X | X | X |  |  |  |  |

## Functions

| Type | GEB13.. $/$ / GEB33... 1 | GEB16.. 1 |
| :---: | :---: | :---: |
| Control type | Three-position control | Modulating control |
| Positioning signal with adjustable characteristic function |  | $\begin{array}{cl} \hline \text { DC } 0 \ldots . .35 \mathrm{~V} \text { with } \\ \text { Offset } & U 0=0 \ldots 5 \mathrm{~V} \text { and } \\ \text { span } & \Delta U=2 . .30 \mathrm{~V} \\ \hline \end{array}$ |
| Rotary direction | Clockwise or counter-clockwise direction depends... |  |
|  | ....the type of control. With no power applied, the actuator remains in the respective position. | ...the DIL switch setting clockwise / counterclockwise |
| Position indication: Mechanical | Rotary angle position indication by using a position indicator. |  |
| Position indication: Electrical | The feedback potentiometer can be connected to external voltage to indicate the position. | Position indicator: <br> Output voltage $\mathrm{U}=\mathrm{DC} 0 \ldots 10 \mathrm{~V}$ is generated proportional to the rotary angle. U depends on the rotary direction of the DIL switch. |
| Auxiliary switch | The switching points for auxiliary switches A and B can be set independent of each other in increments of $5^{\circ}$ within $0^{\circ}$ to $90^{\circ}$. |  |
| Self-adaptation of rotary angle range |  | When self-adaptation is active, the actuator automatically determines the mechanical end positions of the rotary angle range and maps the characteristic function ( $\mathrm{Uo}, \Delta \mathrm{U}$ ) to the calculated rotary angle range. |
| Powerpack | Mounting two of the same actuator types on the same damper shaft may result in a double torque. | Not permitted. |
| Rotary angle limitation | The rotary angle of the shaft adapter can be limited mechanically at increments of $5^{\circ}$. |  |

## Ordering

Note Potentiometer and auxiliary switches cannot be added in the field. For this reason, order the type that includes the required options.
Delivery Individual parts such as position indicator and other mounting materials for the actuator are not mounted on delivery.

Accessories, spare parts

Accessories to functionally extend the actuators are available, e.g., rotary/linear sets and weather protection cover; see data sheet N4697.

## Technical data

AC 24 V supply
(SELV/PELV)

AC 230 V supply
Function data

Positioning signal for GEB16.. 1
Characteristic functions
for GEB161.1, GEB166.1
for GEB163.1, GEB164.1

Position indicator
for GEB16... 1
Feedback potentiometer
for GEB132.1 / GEB332.1
! Auxiliary switches
for GEB..6.1 / GEB164.1

Connection cables
Degree of protection of housing
Protection class

Environmental conditions

Standards and directives

Dimensions

Weight

| Operating voltage / Frequency | AC $24 \mathrm{~V} \pm 20 \% / 50 / 60 \mathrm{~Hz}$ |
| :---: | :---: |
| Power consumption GEB13..1: Running | $4 \mathrm{VA} / 3.5 \mathrm{~W}$ |
| GEB16..1: Running | $6 \mathrm{VA} / 5.5 \mathrm{~W}$ |
| Holding | 1.5 W |
| Operating voltage / Frequency | AC $230 \mathrm{~V} \pm 10 \% / 50 / 60 \mathrm{~Hz}$ |
| Power consumption GEB33.. 1 | $3 \mathrm{VA} / 3 \mathrm{~W}$ |
| Nominal torque | 15 Nm |
| Maximum torque (blocked) | 30 Nm |
| Nominal rotary angle / Max. rotary angle | $90^{\circ} /$ max. $95^{\circ} \pm 2^{\circ}$ |
| Runtime for $90^{\circ}$ rotary angle | $150 \mathrm{~s}(50 \mathrm{~Hz}) / 125 \mathrm{~s}(60 \mathrm{~Hz})$ |
| Input voltage Y (wires 8-2) | DC 0... $10 \mathrm{~V} / \mathrm{DC} 2 \ldots 10 \mathrm{~V}$ |
| Max. permissible input voltage | DC 35 V |
| Input voltage Y (wires 8-2) | DC 0... 35 V |
| Non-adjustable characteristic function | DC 0... $10 \mathrm{~V} / \mathrm{DC} 2 \ldots .10 \mathrm{~V}$ |
| Adjustable characteristic function Offset Uo | DC 0... 5 V |
| Span $\Delta \mathrm{U}$ | DC $2 . . .30 \mathrm{~V}$ |
| Output voltage U (cores 9-2) | DC 0... 10 V |
| Max. output current | DC $\pm 1 \mathrm{~mA}$ |
| Change of resistance (wires P1-P2) | 0... $1000 \Omega$ |
| Load | $<1 \mathrm{~W}$ |
| Contact rating | 6 A resistive, 2 A inductive |
| Voltage (no mixed operation AC $24 \mathrm{~V} / \mathrm{AC} 230 \mathrm{~V}$ ) | AC 24... 230 V |
| Switching range for auxiliary switches | $5^{\circ} \ldots 90^{\circ}$ |
| Setting increments | $5^{\circ}$ |
| Cross-section | $0.75 \mathrm{~mm}^{2}$ |
| Standard length | 0.9 m |
| Degree of protection as per EN 60529 (note mounting instructio | IP 54 |
| Insulation class | EN 60730 |
| AC 24 V , feedback potentiometer | III |
| AC 230 V , auxiliary switch | II |
| Operation / Transport | IEC 721-3-3 / IEC 721-3-2 |
| Temperature | $-32 \ldots+55^{\circ} \mathrm{C} /-32 \ldots+70^{\circ} \mathrm{C}$ |
| Humidity (non-condensing) | <95\% r. h. $/<95 \%$ r. h. |
| Product safety: Automatic electrical controls for household and similar use | EN 60 730-2-14 <br> (Type 1) |
| Electromagnetic compatibility (EMC): |  |
| Immunity for all models, except GEB132.1x; GEB332.1x | EN 61 000-6-2 |
| Immunity for GEB132.1x; GEB332.1x | EN 50 082-1 |
| Emissions for all models | EN 50 081-1 |
| ( $\in$ Conformity: |  |
| Electromagnetic compatibility | 89/336/EEC |
| Low voltage directive | 73/23/EEC |
| ( Conformity: |  |
| Australian EMC Framework | Radio Communication Act 1992 |
| Radio Interference Emission Standard | AS/NZS 3548 |
| Actuator W x H x D (see "Dimensions") | $81 \times 192 \times 63 \mathrm{~mm}$ |
| Damper shaft: Round | $6.4 . .20 .5 \mathrm{~mm}$ |
| Square | $6.4 \ldots 13 \mathrm{~mm}$ |
| Min. shaft length | 20 mm |
| Without packaging: GEB1...1 | 1 kg |
| GEB33.. 1 | 1.1 kg |

## Disposal

The document on technical basics and the environmental declaration provide information on environmental compatibility and disposal of this device.


Cable labeling

| Pin | Cable |  |  |  | Meaning |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Code | No. | Color Abbreviation |  |  |
| Actuators AC 24 V | $\begin{aligned} & \mathrm{G} \\ & \mathrm{G} 0 \\ & \mathrm{Y} 1 \\ & \mathrm{Y} 2 \\ & \mathrm{Y} \\ & \mathrm{U} \\ & \hline \end{aligned}$ | $\begin{array}{\|l} 1 \\ 2 \\ 6 \\ 7 \\ 7 \\ 8 \\ 9 \end{array}$ | red <br> black <br> purple <br> orange <br> gray <br> pink | RD BK <br> VT <br> OG <br> GY <br> PK | System potential AC 24 V <br> System neutral <br> Control signal AC 0 V, clockwise <br> Control signal AC 0 V, counter-clockwise <br> Pos. signal DC $0 . . .10 \mathrm{~V}, 2 \ldots 10 \mathrm{~V}, 0 \ldots 35 \mathrm{~V}$ <br> Position indication DC $0 . . .10 \mathrm{~V}$ |
| Actuators AC 230V | $\begin{aligned} & \mathrm{N} \\ & \mathrm{Y} 1 \\ & \mathrm{Y} 2 \end{aligned}$ | $\begin{aligned} & 4 \\ & 6 \\ & 7 \end{aligned}$ | blue black white | BU <br> BK <br> WH | Neutral conductor <br> Control signal AC 230 V, clockwise <br> Control signal AC 230 V, counter-clockwise |
| Auxiliary switch | Q11 Q12 Q14 Q21 Q22 Q24 | $\begin{aligned} & \text { S1 } \\ & \text { S2 } \\ & \text { S3 } \\ & \text { S4 } \\ & \text { S5 } \\ & \text { S } \end{aligned}$ | gray/red gray/blue gray/pink black/red black/blue black/pink | GY RD <br> GY BU <br> GY PK <br> BK RD <br> BK BU <br> BK PK | Switch A Input <br> Switch A Normally closed contact <br> Switch A Normally open contact <br> Switch B Input <br> Switch B Normally closed contact <br> Switch B Normally open contact |
| Positioner | $\begin{aligned} & \mathrm{a} \\ & \mathrm{~b} \\ & \mathrm{c} \end{aligned}$ | $\begin{aligned} & \text { P1 } \\ & \text { P2 } \\ & \text { P3 } \end{aligned}$ | white/red white/blue white/pink | $\begin{aligned} & \text { WH RD } \\ & \text { WH BU } \\ & \text { WH PK } \end{aligned}$ | Potentiometer 0... 100 \% (P1-P2) <br> Potentiometer pick-off <br> Potentiometer 100... 0 \% (P3-P2) |

Dimensions


Mounting bracket

Dimensions in mm

Subject to change

